

An Ant Colony Optimization Algorithm for the Two-Stage Knapsack Problem

Stefanie Kosuch

Postdoc at the Theoretical Computer Science Lab
Linköpings Universitet (Sweden)

Évolution Artificielle 2011
Angers, France, October 24 - 26, 2011



Linköping University

1 The Two-Stage Knapsack Problem



1 The Two-Stage Knapsack Problem

2 The ACO-algorithm



- 1 The Two-Stage Knapsack Problem
- 2 The ACO-algorithm
- 3 Summary of Numerical Results



- 1 The Two-Stage Knapsack Problem
- 2 The ACO-algorithm
- 3 Summary of Numerical Results
- 4 Future Work



Outline

- 1 The Two-Stage Knapsack Problem
- 2 The ACO-algorithm
- 3 Summary of Numerical Results
- 4 Future Work



The Deterministic Knapsack Problem



The Deterministic Knapsack Problem

- $c > 0$: Knapsack weight capacity



The Deterministic Knapsack Problem

- $c > 0$: Knapsack weight capacity
- n items



The Deterministic Knapsack Problem

- $c > 0$: Knapsack weight capacity
- n items
- $r_i > 0$: reward of item i



The Deterministic Knapsack Problem

- $c > 0$: Knapsack weight capacity
- n items
- $r_i > 0$: reward of item i
- w_i : weight of item i



The Deterministic Knapsack Problem

- $c > 0$: Knapsack weight capacity
- n items
- $r_i > 0$: reward of item i
- w_i : weight of item i

Objective

Maximize the total reward of chosen items whose total weight respect knapsack capacity.



The Deterministic Knapsack Problem

- $c > 0$: Knapsack weight capacity
- n items
- $r_i > 0$: reward of item i
- w_i : weight of item i

Objective

Maximize the total reward of chosen items whose total weight respect knapsack capacity.

Applications

Logistics - Resource allocation - Scheduling - Network Optimization etc.

The **Stochastic** Knapsack Problem **with Random Weights**

- $c > 0$: Knapsack weight capacity
- n items
- $r_i > 0$: reward of item i
- χ_i : **random** weight of item i

Objective

Maximize the total reward of chosen items whose total weight respect knapsack capacity.



The **Stochastic Knapsack Problem with Random Weights**

- $c > 0$: Knapsack weight capacity
- n items
- $r_i > 0$: reward of item i
- χ_i : **random** weight of item i
weight unknown when decision has to be made

Objective

Maximize the total reward of chosen items whose total weight respect knapsack capacity.



The **Stochastic Knapsack Problem with Random Weights**

- $c > 0$: Knapsack weight capacity
- n items
- $r_i > 0$: reward of item i
- χ_i : **random** weight of item i
weight unknown when decision has to be made

Objective

Maximize the total reward of chosen items whose total weight respect knapsack capacity.

Question

How to handle the fact that chosen items might not respect knapsack capacity?

Two-Stage Setting



Two-Stage Setting

- First stage: items can be put in the knapsack



Two-Stage Setting

- First stage: items can be put in the knapsack
- First stage \longleftrightarrow second stage: item weights are revealed



Two-Stage Setting

- First stage: items can be put in the knapsack
- First stage \longleftrightarrow second stage: item weights are revealed
- Second stage: The decision can/has to be corrected



Two-Stage Setting

- First stage: items can be put in the knapsack
- First stage \longleftrightarrow second stage: item weights are revealed
- Second stage: Items
 - ...have to be removed in case of an overweight
 - ...can be added if capacity sufficient
 - ...can be exchanged to increase gain.



Two-Stage Setting

- First stage: items can be put in the knapsack
- First stage \longleftrightarrow second stage: item weights are revealed
- Second stage: Items
 - ...have to be removed in case of an overweight
 - ...can be added if capacity sufficient
 - ...can be exchanged to increase gain.
- Correction of the decision causes penalty



Two-Stage Setting

- First stage: items can be put in the knapsack
- First stage \longleftrightarrow second stage: item weights are revealed
- Second stage: Items
 - ...have to be removed in case of an overweight
 - ...can be added if capacity sufficient
 - ...can be exchanged to increase gain.
- Correction of the decision causes penalty

Assumption: Discretely distributed weights



Two-Stage Setting

- First stage: items can be put in the knapsack
- First stage \longleftrightarrow second stage: item weights are revealed
- Second stage: Items
 - ...have to be removed in case of an overweight
 - ...can be added if capacity sufficient
 - ...can be exchanged to increase gain.
- Correction of the decision causes penalty

Assumption: Discretely distributed weights

- K **scenarios**



Two-Stage Setting

- First stage: items can be put in the knapsack
- First stage \longleftrightarrow second stage: item weights are revealed
- Second stage: Items
 - ...have to be removed in case of an overweight
 - ...can be added if capacity sufficient
 - ...can be exchanged to increase gain.
- Correction of the decision causes penalty

Assumption: Discretely distributed weights

- K **scenarios**
- K **realizations** χ^1, \dots, χ^K



Two-Stage Setting

- First stage: items can be put in the knapsack
- First stage \longleftrightarrow second stage: item weights are revealed
- Second stage: Items
 - ...have to be removed in case of an overweight
 - ...can be added if capacity sufficient
 - ...can be exchanged to increase gain.
- Correction of the decision causes penalty

Assumption: Discretely distributed weights

- K scenarios
- K realizations χ^1, \dots, χ^K
- $\mathbb{P}\{\chi = \chi^k\} = p^k$



Two-Stage Knapsack Problem



Two-Stage Knapsack Problem

$$(TSKP) \quad \max_{x \in \{0,1\}^n} \sum_{i=1}^n r_i x_i$$

s.t.

x : decision vector of 1st stage



Two-Stage Knapsack Problem

$$\begin{aligned}
 (TSKP) \quad & \max_{x \in \{0,1\}^n} \sum_{i=1}^n r_i x_i + \mathbb{E}[Q(x, \chi)] \\
 \text{s.t.} \quad & Q(x, \chi) = \max_{y^+, y^- \in \{0,1\}^n} \sum_{i=1}^n \bar{r}_i y_i^+ - \sum_{i=1}^n d_i y_i^-,
 \end{aligned}$$

x : decision vector of 1st stage

y^+, y^- : decision vectors of 2nd stage (recourse action)

$\bar{r}_i < r_i, d_i > r_i$



Two-Stage Knapsack Problem

$$\begin{aligned}
 (\text{TSKP}) \quad & \max_{x \in \{0,1\}^n} \sum_{i=1}^n r_i x_i + \mathbb{E}[Q(\mathbf{x}, \chi)] \\
 \text{s.t.} \quad & Q(x, \chi) = \max_{\mathbf{y}^+, \mathbf{y}^- \in \{0,1\}^n} \sum_{i=1}^n \bar{r}_i y_i^+ - \sum_{i=1}^n d_i y_i^-,
 \end{aligned}$$

x : decision vector of 1st stage

$\mathbf{y}^+, \mathbf{y}^-$: decision vectors of 2nd stage (recourse action)

$\bar{r}_i < r_i, d_i > r_i$



Two-Stage Knapsack Problem

$$\begin{aligned}
 (\text{TSKP}) \quad & \max_{x \in \{0,1\}^n} \sum_{i=1}^n r_i x_i + \mathbb{E}[Q(\mathbf{x}, \chi)] \\
 \text{s.t.} \quad & Q(\mathbf{x}, \chi) = \max_{\mathbf{y}^+, \mathbf{y}^- \in \{0,1\}^n} \sum_{i=1}^n \bar{r}_i y_i^+ - \sum_{i=1}^n \mathbf{d}_i y_i^-,
 \end{aligned}$$

x : decision vector of 1st stage

$\mathbf{y}^+, \mathbf{y}^-$: decision vectors of 2nd stage (recourse action)

$\bar{r}_i < r_i, \mathbf{d}_i > r_i$



Two-Stage Knapsack Problem

$$\begin{aligned}
 (\text{TSKP}) \quad & \max_{x \in \{0,1\}^n} \sum_{i=1}^n r_i x_i + \mathbb{E}[Q(x, \chi)] \\
 \text{s.t.} \quad & Q(x, \chi) = \max_{y^+, y^- \in \{0,1\}^n} \sum_{i=1}^n \bar{r}_i y_i^+ - \sum_{i=1}^n d_i y_i^-,
 \end{aligned}$$

x : decision vector of 1st stage

y^+, y^- : decision vectors of 2nd stage (recourse action)

$\bar{r}_i < r_i, d_i > r_i$



Two-Stage Knapsack Problem

$$\begin{aligned}
 (\text{TSKP}) \quad & \max_{\mathbf{x} \in \{0,1\}^n} \sum_{i=1}^n r_i x_i + \mathbb{E}[Q(\mathbf{x}, \chi)] \\
 \text{s.t.} \quad & Q(\mathbf{x}, \chi) = \max_{\mathbf{y}^+, \mathbf{y}^- \in \{0,1\}^n} \sum_{i=1}^n \bar{r}_i y_i^+ - \sum_{i=1}^n \mathbf{d}_i y_i^-, \\
 \text{s.t.} \quad & y_j^+ \leq 1 - x_j, \quad j = 1, \dots, n, \\
 & y_j^- \leq x_j, \quad j = 1, \dots, n,
 \end{aligned}$$

\mathbf{x} : decision vector of 1st stage

$\mathbf{y}^+, \mathbf{y}^-$: decision vectors of 2nd stage (recourse action)

$\bar{r}_i < r_i, \mathbf{d}_i > r_i$



Two-Stage Knapsack Problem

$$\begin{aligned}
 (\text{TSKP}) \quad & \max_{\mathbf{x} \in \{0,1\}^n} \sum_{i=1}^n r_i x_i + \mathbb{E}[Q(\mathbf{x}, \chi)] \\
 \text{s.t.} \quad & Q(\mathbf{x}, \chi) = \max_{\mathbf{y}^+, \mathbf{y}^- \in \{0,1\}^n} \sum_{i=1}^n \bar{r}_i y_i^+ - \sum_{i=1}^n \mathbf{d}_i y_i^-, \\
 \text{s.t.} \quad & y_j^+ \leq 1 - x_j, \quad j = 1, \dots, n, \\
 & y_j^- \leq x_j, \quad j = 1, \dots, n, \\
 & \sum_{i=1}^n (x_i + y_i^+ - y_i^-) \chi_i \leq c.
 \end{aligned}$$

\mathbf{x} : decision vector of 1st stage

$\mathbf{y}^+, \mathbf{y}^-$: decision vectors of 2nd stage (recourse action)

$\bar{r}_i < r_i, \mathbf{d}_i > r_i$



Two-Stage Knapsack Problem

$$\begin{aligned}
 (\text{TSKP}) \quad & \max_{\mathbf{x} \in \{0,1\}^n} \sum_{i=1}^n r_i x_i + \mathbb{E}[Q(\mathbf{x}, \chi)] \\
 \text{s.t.} \quad & Q(\mathbf{x}, \chi) = \max_{\mathbf{y}^+, \mathbf{y}^- \in \{0,1\}^n} \sum_{i=1}^n \bar{r}_i y_i^+ - \sum_{i=1}^n \mathbf{d}_i y_i^-, \\
 \text{s.t.} \quad & y_j^+ \leq 1 - x_j, \quad j = 1, \dots, n, \\
 & y_j^- \leq x_j, \quad j = 1, \dots, n, \\
 & \sum_{i=1}^n (x_i + y_i^+ - y_i^-) \chi_i \leq c.
 \end{aligned}$$

\mathbf{x} : decision vector of 1st stage

$\mathbf{y}^+, \mathbf{y}^-$: decision vectors of 2nd stage (recourse action)

$\bar{r}_i < r_i, \mathbf{d}_i > r_i$



Two-Stage Knapsack Problem

$$\begin{aligned}
 (TSKP) \quad & \max_{x \in \{0,1\}^n} \sum_{i=1}^n r_i x_i + \sum_{k=1}^K p^k Q(x, \chi^k) \\
 \text{s.t.} \quad & Q(x, \chi) = \max_{y^+, y^- \in \{0,1\}^n} \sum_{i=1}^n \bar{r}_i y_i^+ - \sum_{i=1}^n d_i y_i^-, \\
 \text{s.t.} \quad & y_j^+ \leq 1 - x_j, \quad j = 1, \dots, n, \\
 & y_j^- \leq x_j, \quad j = 1, \dots, n, \\
 & \sum_{i=1}^n (x_i + y_i^+ - y_i^-) \chi_i \leq c.
 \end{aligned}$$

x : decision vector of 1st stage

y^+, y^- : decision vectors of 2nd stage (recourse action)

$\bar{r}_i < r_i, d_i > r_i$



Outline

- 1 The Two-Stage Knapsack Problem
- 2 The ACO-algorithm**
- 3 Summary of Numerical Results
- 4 Future Work



Natural idea: try metaheuristics!



But why an **ACO**-metaheuristic?



But why an **ACO**-metaheuristic?

- Possibility to use **heuristic utility measures**



But why an **ACO**-metaheuristic?

- Possibility to use **heuristic utility measures**
- Construction of solution → **no evaluation**



But why an **ACO**-metaheuristic?

- Possibility to use **heuristic utility measures**
- Construction of solution → **no evaluation**
- Obj. func. evaluation ← comparison



Two-Stage Knapsack Problem

$$\begin{aligned}
 (TSKP) \quad & \max_{\mathbf{x} \in \{0,1\}^n} \sum_{i=1}^n r_i x_i + \sum_{k=1}^K \mathbf{p}^k Q(\mathbf{x}, \chi^k) \\
 \text{s.t.} \quad & Q(\mathbf{x}, \chi) = \max_{\mathbf{y}^+, \mathbf{y}^- \in \{0,1\}^n} \sum_{i=1}^n \bar{r}_i y_i^+ - \sum_{i=1}^n \mathbf{d}_i y_i^-, \\
 \text{s.t.} \quad & y_j^+ \leq 1 - x_j, \quad j = 1, \dots, n, \\
 & y_j^- \leq x_j, \quad j = 1, \dots, n, \\
 & \sum_{i=1}^n (x_i + y_i^+ - y_i^-) \chi_i \leq c.
 \end{aligned}$$

\mathbf{x} : decision vector of 1st stage

$\mathbf{y}^+, \mathbf{y}^-$: decision vectors of 2nd stage (recourse action)

$\bar{r}_i < r_i, \mathbf{d}_i > r_i$



The search graph



The search graph

- **Complete directed** search graph: n vertices $\simeq n$ items



The search graph

- **Complete directed** search graph: n vertices $\simeq n$ items
- Pheromone laid on **arcs** (directed edges)



The search graph

- **Complete directed** search graph: n vertices $\simeq n$ items
- Pheromone laid on **arcs** (directed edges)
- Add **starting vertex**



The search graph

- **Complete directed** search graph: n vertices $\simeq n$ items
- Pheromone laid on **arcs** (directed edges)
- Add **starting vertex**
- Add **termination vertex**



Heuristic utility measure I: Problems



Heuristic utility measure I: Problems

- 4 factors to be considered:



Heuristic utility measure I: Problems

- 4 factors to be considered:
 - item weight
 - first-stage reward
 - second-stage reward
 - second-stage penalty



Heuristic utility measure I: Problems

- 4 factors to be considered:
 - item weight
 - first-stage reward
 - second-stage reward
 - second-stage penalty
- K different weights per item



Heuristic utility measure I: Problems

- 4 factors to be considered:
 - item weight
 - first-stage reward
 - second-stage reward
 - second-stage penalty
- K different weights per item
- no "natural" certificate for termination



Heuristic utility measure I: Problems

- 4 factors to be considered:
 - item weight
 - first-stage reward
 - second-stage reward
 - second-stage penalty
- K different weights per item
- no "natural" certificate for termination
- utility measure for termination vertex → via **non-utility measure**



Heuristic utility measure II: Simple measure

Heuristic utility measure II: Simple measure

\mathcal{K}_i : set of scenarios where item i still fits

- Simple utility measure ($i \in \{1, \dots, n\}$):

$$\eta_i^S = \sum_{k \in \mathcal{K}_i} p^k \frac{r_i}{\chi_i^k}$$

Heuristic utility measure II: Simple measure

\mathcal{K}_i : set of scenarios where item i still fits

- Simple utility measure ($i \in \{1, \dots, n\}$):

$$\eta_i^S = \sum_{k \in \mathcal{K}_i} p^k \frac{r_i}{\chi_i^k}$$

- Simple non-utility measure ($i \in \{1, \dots, n\}$):

$$\nu_i^S = \sum_{k \notin \mathcal{K}_i} p^k \frac{d_i}{\chi_i^k} \quad \nu_i^S = \sum_{k=1}^K p^k \frac{\bar{r}_i}{\chi_i^k}$$

Heuristic utility measure II: Simple measure

\mathcal{K}_i : set of scenarios where item i still fits

- Simple utility measure ($i \in \{1, \dots, n\}$):

$$\eta_i^S = \sum_{k \in \mathcal{K}_i} p^k \frac{r_i}{\chi_i^k}$$

- Simple non-utility measure ($i \in \{1, \dots, n\}$):

$$\nu_i^S = \sum_{k \notin \mathcal{K}_i} p^k \frac{d_i}{\chi_i^k} \quad \nu_i^S = \sum_{k=1}^K p^k \frac{\bar{r}_i}{\chi_i^k}$$

Utility of termination:

$$\eta_{n+1}^S = \min_{i \in \{1, \dots, n\}} \nu_i^S$$

Heuristic utility measure III: Difference measure

Heuristic utility measure III: Difference measure

\mathcal{K}_i : set of scenarios where item i still fits

- Difference utility measure ($i \in \{1, \dots, n\}$):

$$\eta_i^D = \sum_{k \in \mathcal{K}_i} p^k \frac{r_i - \bar{r}_i}{\chi_i^k}$$

Heuristic utility measure III: Difference measure

\mathcal{K}_i : set of scenarios where item i still fits

- Difference utility measure ($i \in \{1, \dots, n\}$):

$$\eta_i^D = \sum_{k \in \mathcal{K}_i} p^k \frac{r_i - \bar{r}_i}{\chi_i^k}$$

- Difference non-utility measure ($i \in \{1, \dots, n\}$):

$$\nu_i^D = \sum_{k \notin \mathcal{K}_i} p^k \frac{d_i - r_i}{\chi_i^k}$$

Heuristic utility measure III: Difference measure

\mathcal{K}_i : set of scenarios where item i still fits

- Difference utility measure ($i \in \{1, \dots, n\}$):

$$\eta_i^D = \sum_{k \in \mathcal{K}_i} p^k \frac{r_i - \bar{r}_i}{\chi_i^k}$$

- Difference non-utility measure ($i \in \{1, \dots, n\}$):

$$\nu_i^D = \sum_{k \notin \mathcal{K}_i} p^k \frac{d_i - r_i}{\chi_i^k}$$

Utility of termination:

$$\eta_{n+1}^D = \min_{i \in \{1, \dots, n\}} \nu_i^D$$

Outline

- 1 The Two-Stage Knapsack Problem
- 2 The ACO-algorithm
- 3 Summary of Numerical Results**
- 4 Future Work

Numerical Tests

- $n \in \{100, 250\}$, $K \in \{5, 10, 30\}$, $t \in \{0.25, 0.5, 0.75\}$



Numerical Tests

- $n \in \{100, 250\}$, $K \in \{5, 10, 30\}$, $t \in \{0.25, 0.5, 0.75\}$
- 36 instances, 50 runs per instance



Numerical Tests

- $n \in \{100, 250\}$, $K \in \{5, 10, 30\}$, $t \in \{0.25, 0.5, 0.75\}$
- 36 instances, 50 runs per instance
- hard instances (CPLEX $> 2h$)



Numerical Tests

- $n \in \{100, 250\}$, $K \in \{5, 10, 30\}$, $t \in \{0.25, 0.5, 0.75\}$
- 36 instances, 50 runs per instance
- hard instances (CPLEX $> 2h$)



Numerical Tests

- $n \in \{100, 250\}$, $K \in \{5, 10, 30\}$, $t \in \{0.25, 0.5, 0.75\}$
- 36 instances, 50 runs per instance
- hard instances (CPLEX $> 2h$)

Observations $n = 100$



Numerical Tests

- $n \in \{100, 250\}$, $K \in \{5, 10, 30\}$, $t \in \{0.25, 0.5, 0.75\}$
- 36 instances, 50 runs per instance
- hard instances (CPLEX $> 2h$)

Observations $n = 100$

- Difference measure "outperforms" Simple measure



Numerical results

n-K-t	Difference measure			Simple measure		
	Succesf. runs	Av. gap	Time (s)	Succesf. runs	Av. gap	Time (s)
100-5-0.25	57 %	0.02 %	35	13 %	0.05 %	30
100-5-0.5	28 %	0.01 %	57	1 %	0.03 %	52
100-5-0.75	1 %	0.02 %	69	0 %	0.02 %	71
100-10-0.25	93 %	0.06 %	47	63 %	0.01 %	34
100-10-0.5	23 %	0.01 %	72	0 %	0.03 %	63
100-10-0.75	15 %	0.02 %	85	0 %	0.04 %	85
100-30-0.25	58 %	0.02 %	147	0 %	0.12 %	107
100-30-0.5	63 %	0.01 %	232	8 %	0.02 %	179
100-30-0.75	25 %	0.01 %	295	0 %	0.03 %	183
250-30-0.25	0 %	0.04 %	414	N/T	N/T	N/T
250-30-0.5	0 %	0.06 %	592	N/T	N/T	N/T
250-30-0.75	0 %	0.06 %	835	N/T	N/T	N/T

Numerical Tests

- $n \in \{100, 250\}$, $K \in \{5, 10, 30\}$, $t \in \{0.25, 0.5, 0.75\}$
- 36 instances, 50 runs per instance
- hard instances (CPLEX $> 2h$)

Observations $n = 100$

- Difference measure "outperforms" Simple measure



Numerical Tests

- $n \in \{100, 250\}$, $K \in \{5, 10, 30\}$, $t \in \{0.25, 0.5, 0.75\}$
- 36 instances, 50 runs per instance
- hard instances (CPLEX $> 2h$)

Observations $n = 100$

- Difference measure "outperforms" Simple measure
- Very small average gaps ($\sim 0.02\%$)



Numerical Tests

- $n \in \{100, 250\}$, $K \in \{5, 10, 30\}$, $t \in \{0.25, 0.5, 0.75\}$
- 36 instances, 50 runs per instance
- hard instances (CPLEX $> 2h$)

Observations $n = 100$

- Difference measure "outperforms" Simple measure
- Very small average gaps ($\sim 0.02\%$)
- Relative performance to CPLEX increases with K



Numerical results

n-K-t	Difference measure			Simple measure		
	Succesf. runs	Av. gap	Time (s)	Succesf. runs	Av. gap	Time (s)
100-5-0.25	57 %	0.02 %	35	13 %	0.05 %	30
100-5-0.5	28 %	0.01 %	57	1 %	0.03 %	52
100-5-0.75	1 %	0.02 %	69	0 %	0.02 %	71
100-10-0.25	93 %	0.06 %	47	63 %	0.01 %	34
100-10-0.5	23 %	0.01 %	72	0 %	0.03 %	63
100-10-0.75	15 %	0.02 %	85	0 %	0.04 %	85
100-30-0.25	58 %	0.02 %	147	0 %	0.12 %	107
100-30-0.5	63 %	0.01 %	232	8 %	0.02 %	179
100-30-0.75	25 %	0.01 %	295	0 %	0.03 %	183
250-30-0.25	0 %	0.04 %	414	N/T	N/T	N/T
250-30-0.5	0 %	0.06 %	592	N/T	N/T	N/T
250-30-0.75	0 %	0.06 %	835	N/T	N/T	N/T



Numerical Tests

- $n \in \{100, 250\}$, $K \in \{5, 10, 30\}$, $t \in \{0.25, 0.5, 0.75\}$
- 36 instances, 50 runs per instance
- hard instances (CPLEX $> 2h$)

Observations $n = 100$

- Difference measure "outperforms" Simple measure
- Very small average gaps ($\sim 0.02\%$)
- Relative performance to CPLEX increases with K



Numerical Tests

- $n \in \{100, 250\}$, $K \in \{5, 10, 30\}$, $t \in \{0.25, 0.5, 0.75\}$
- 36 instances, 50 runs per instance
- hard instances (CPLEX $> 2h$)

Observations $n = 100$

- Difference measure "outperforms" Simple measure
- Very small average gaps ($\sim 0.02\%$)
- Relative performance to CPLEX increases with K
- Average Time $< 1\text{min}$ ($< 1.5\text{min}$, $< 5\text{min}$)



Numerical Tests

- $n \in \{100, 250\}$, $K \in \{5, 10, 30\}$, $t \in \{0.25, 0.5, 0.75\}$
- 36 instances, 50 runs per instance
- hard instances (CPLEX $> 2h$)

Observations $n = 100$

- Difference measure "outperforms" Simple measure
- Very small average gaps ($\sim 0.02\%$)
- Relative performance to CPLEX increases with K
- Average Time $< 1\text{min}$ ($< 1.5\text{min}$, $< 5\text{min}$)



Numerical Tests

- $n \in \{100, 250\}$, $K \in \{5, 10, 30\}$, $t \in \{0.25, 0.5, 0.75\}$
- 36 instances, 50 runs per instance
- hard instances (CPLEX $> 2h$)

Observations $n = 100$

- Difference measure "outperforms" Simple measure
- Very small average gaps ($\sim 0.02\%$)
- Relative performance to CPLEX increases with K
- Average Time $< 1\text{min}$ ($< 1.5\text{min}$, $< 5\text{min}$)

Observations $n = 250$

Numerical Tests

- $n \in \{100, 250\}$, $K \in \{5, 10, 30\}$, $t \in \{0.25, 0.5, 0.75\}$
- 36 instances, 50 runs per instance
- hard instances (CPLEX $> 2h$)

Observations $n = 100$

- Difference measure "outperforms" Simple measure
- Very small average gaps ($\sim 0.02\%$)
- Relative performance to CPLEX increases with K
- Average Time $< 1\text{min}$ ($< 1.5\text{min}$, $< 5\text{min}$)

Observations $n = 250$

- Still small average gaps ($\leq 0.06\%$)

Numerical Tests

- $n \in \{100, 250\}$, $K \in \{5, 10, 30\}$, $t \in \{0.25, 0.5, 0.75\}$
- 36 instances, 50 runs per instance
- hard instances (CPLEX $> 2h$)

Observations $n = 100$

- Difference measure "outperforms" Simple measure
- Very small average gaps ($\sim 0.02\%$)
- Relative performance to CPLEX increases with K
- Average Time $< 1\text{min}$ ($< 1.5\text{min}$, $< 5\text{min}$)

Observations $n = 250$

- Still small average gaps ($\leq 0.06\%$)
- None of instances "solved"

Numerical Tests

- $n \in \{100, 250\}$, $K \in \{5, 10, 30\}$, $t \in \{0.25, 0.5, 0.75\}$
- 36 instances, 50 runs per instance
- hard instances (CPLEX $> 2h$)

Observations $n = 100$

- Difference measure "outperforms" Simple measure
- Very small average gaps ($\sim 0.02\%$)
- Relative performance to CPLEX increases with K
- Average Time $< 1\text{min}$ ($< 1.5\text{min}$, $< 5\text{min}$)

Observations $n = 250$

- Still small average gaps ($\leq 0.06\%$)
- None of instances "solved"
- Ratio Running time/ n increases slightly

Outline

- 1 The Two-Stage Knapsack Problem
- 2 The ACO-algorithm
- 3 Summary of Numerical Results
- 4 Future Work



Future work



Future work

- Improve utility measure for higher n



Future work

- Improve utility measure for higher n
- Consider sampling for higher K



Future work

- Improve utility measure for higher n
- Consider sampling for higher K
- Consider using approximate knapsack algorithm for higher n



Future work

- Improve utility measure for higher n
- Consider sampling for higher K
- Consider using approximate knapsack algorithm for higher n
- **Comparison with other metaheuristics**



Thank you!

:-)

Merci!

