

Stochastic Optimization

IDA PhD course 2011ht

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5. Lecture: Two-Stage Problems

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Linköping University

1 Randomness occurs in the constraint function



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- 2 Simple Recourse problems - Useful Theorems



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- 3 Two-Stage Programming
 - Example: TSKP
 - Simple Recourse as a special case of Two-Stage problems
 - Deterministic reformulation in case of discrete distributions
 - Main theoretical result



Outline

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Deterministic Opt. Model \rightarrow Stochastic Programming Model

$$\begin{array}{ll} \max_{x \in X} & f(x) \\ \text{s.t.} & G(x) \leq 0 \end{array} \quad \rightarrow \quad \begin{array}{ll} \min_{x \in X} & f(x) \\ \text{s.t.} & G(x, \chi) \leq 0 \end{array}$$

$\chi \in \Omega \subseteq \mathbb{R}^s$: random vector

$G : \mathbb{R}^n \times \mathbb{R}^s \rightarrow \mathbb{R}^m$

$G(x, \chi) = (g_1(x, \chi), \dots, g_m(x, \chi))$



Question

What means "feasible solution" in case of uncertain parameters in the constraint function(s)?



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- Feasible in all possible cases → conservative/infeasible/trivial
- Feasible with high probability → chance-constraint ✓
- Average violation not too bad → simple recourse ✓



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- Feasible after correction has been made → multi-stage



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Basic Idea(s)

- Allow violation
- Restrict average "amount of violation"
- Introduce penalty per "violation unit"
- Find good trade-off: cost \leftrightarrow penalty



Simple-Recourse problem



Simple-Recourse problem

$$\min_{x \in X} f(x)$$



Simple-Recourse problem

$$\min_{x \in X} f(x) + \sum_{i=1}^m d_i \cdot \mathbb{E} [[g_i(x, \chi)]^+]$$

- $d_i > 0 \forall i \in \{1, \dots, m\}$



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- $[x]^+ = \max(0, x)$



Theorem

Let

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Then the following holds:

$$g(\cdot, \hat{\chi}) \text{ is convex } \forall \hat{\chi} \implies \gamma \text{ is convex}$$



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Then the following holds:

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- 2 For all $x \in \mathbb{R}^n$ $\gamma(x) < \infty$.

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- 5 $a(\chi)x - b$ discretely distributed $\Rightarrow \gamma$ is piecewise linear.

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- Feasibility in all scenarios: Conservative solutions
- Chance-Constraints: Infeasibility of solution possible
- Simple Recourse: No actual "recourse" action
- In the end: feasible solution → most realistic?
- Costs/rewards of recourse action taken into account



Basic structure of Two-Stage Programming Problem



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- 1 First stage: random parameters unknown



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- 6 Make corrective decision ("recourse"):
 - Make solution feasible
 - Decrease total cost



General Two-Stage Problem



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s.t.

$x \in \mathbb{R}^{n_1}$: decision vector of 1st stage



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$$\min_{x \in X} f^1(x) + \mathbb{E}[Q(x, \chi)]$$

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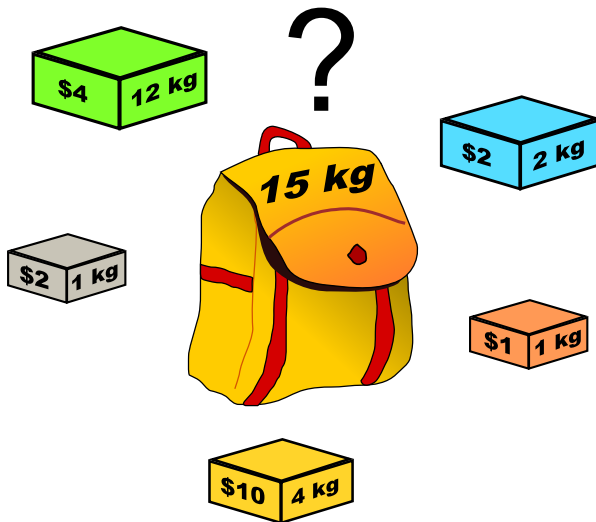


Outline

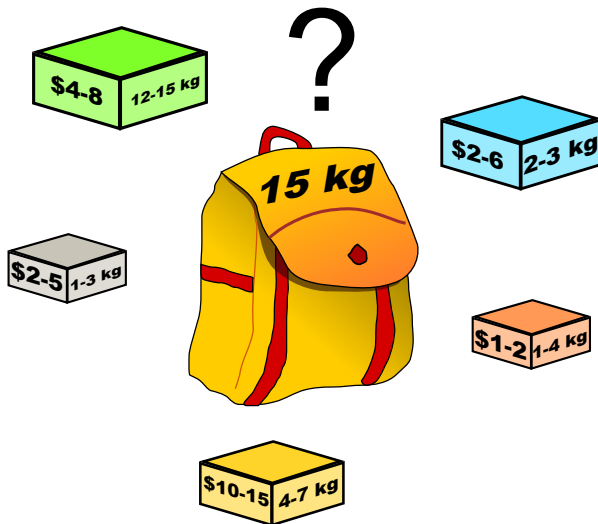
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Two-Stage Stochastic Knapsack problem



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- Correction of the decision causes penalty



Example: TSKP

Application: Travel Agency



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- Knapsack \simeq Hotel Complex
- Weight capacity \simeq Total number of beds
- Items \simeq Travel groups
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→ groups have to be relocated in other hotels
- Vacant beds filled with last minute offers

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$$(TSKP) \quad \max_{x \in \{0,1\}^n} \sum_{i=1}^n r_i x_i$$

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Linear Two-Stage Problem



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$$\min_{x \geq 0} c^T x$$

s.t.

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Linear Two-Stage Problem

$$\begin{aligned} \min_{x \geq 0} \quad & c^T x \\ \text{s.t.} \quad & Ax \geq b, \end{aligned}$$

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$T(\chi)$: Technology matrix

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Linear Simple-Recourse problem



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Equivalent formulation in two stages

$$\begin{aligned} \min_{x \geq 0} \quad & c^T x + \mathbb{E}[Q(x, \chi)] \\ \text{s.t.} \quad & Q(x, \chi) = \min_{y \geq 0} d^T y \\ & \text{s.t.} \quad h(\chi) - T(\chi)x \leq y. \end{aligned}$$

$x \in \mathbb{R}^n$: decision vector of 1st stage

$y \in \mathbb{R}^m$: decision vectors of 2nd stage ("violation")

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\mathbb{I}_n : Identity matrix of dimension n

Simple Recourse Problem formulated as Two-Stage Problem

- No first stage constraints.



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- # second stage variables = # constrains
- $W(\chi) = W = \mathbb{I}_n$



Outline

- 1 Randomness occurs in the constraint function
- 2 Simple Recourse problems - Useful Theorems
- 3 Two-Stage Programming**
 - Example: TSKP
 - Simple Recourse as a special case of Two-Stage problems
 - **Deterministic reformulation in case of discrete distributions**
 - Main theoretical result



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Deterministically Reformulated Linear Two-Stage Problem

$$\min_{x \geq 0} c^T x +$$

$$\text{s.t.} \quad Ax \geq b, \tag{8a}$$



Deterministically Reformulated Linear Two-Stage Problem

$$\begin{aligned} \min_{\substack{x \geq 0 \\ y^k \geq 0}} \quad & c^T x + \sum_{k=1}^K p^k (d^T y^k) \\ \text{s.t.} \quad & Ax \geq b, \end{aligned} \tag{8a}$$



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A Linear Two Stage Programming Problem is said to have **fixed recourse** if the recourse matrix is deterministic, i.e. $W(\chi) = W$.



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$T(\chi)$: Technology matrix

$W(\chi)$: Recourse matrix



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Then $\mathbb{E}[Q(x, \chi)]$ is

- *real-valued,*
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- *Lipschitz continuous in x ,*
- *subdifferentiable in x ,*
- *a polyhedral convex function.*

QUESTIONS?

What about next week?

